



Overview:

In this lesson, students will learn how to create rotary motion using Kid Spark engineering materials. Students will build a simple gear train and observe how it creates rotary motion. Then, students will work as a team to create a custom design that produces rotary motion.

[Click here](#) to explore the entire Kid Spark Curriculum Library.

Learning Objectives & NGSS Alignment:

- ⚙ Define rotary motion.
- ⚙ Build a gear train and observe how it creates rotary motion.
- ⚙ Create a custom design that produces rotary motion.

Scientific/Engineering Practice - Asking questions & defining problems

Crosscutting Concept - Cause & effect; mechanism & explanation

Activity Time:

120 Minutes

Targeted Grade Level:

2 - 5

Student Grouping:

Teams of up to 4 students

Additional Lesson Materials:

- Teacher Lesson Plan
- Student Engineering Workbook

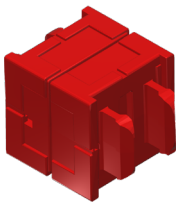
Kid Spark STEM Lab:

STEM Pathways **or**
Engineering Pathways (w/Spark:bit)

Convergent Learning Activity:

1. Exploring Rotary Motion

Rotary motion is motion that turns round in a circle. There are several Kid Spark engineering materials that can be used to produce rotary motion, including the axle block and the snap-in wheel.



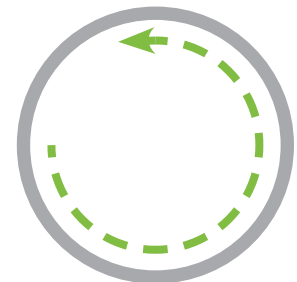
Axle Block



Snap-In Wheel

Rotary Motion

- Turning round in a circle -



Instructions:

Step 1: Locate an axle block and a snap-in wheel. Observe how they create rotary motion.

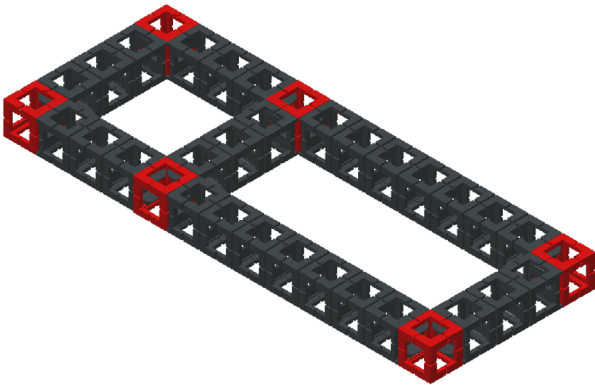
Step 2: Try and locate a few additional engineering materials in the Kid Spark Lab that produce rotary motion.


Step 3: Discuss some real-world examples of rotary motion.

Instructions:


Follow the step-by-step instructions to assemble a simple gear train that produces rotary motion.

1






2x
Beams

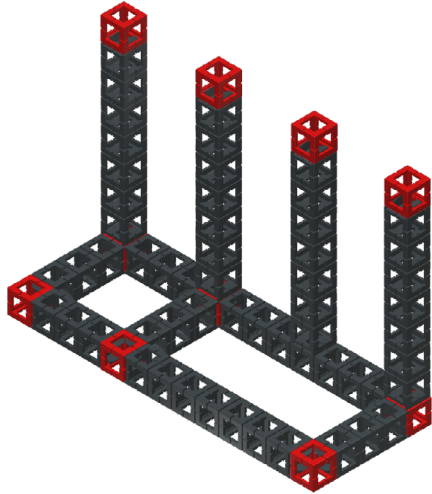



5x
Half Beams




6x
Blocks

2



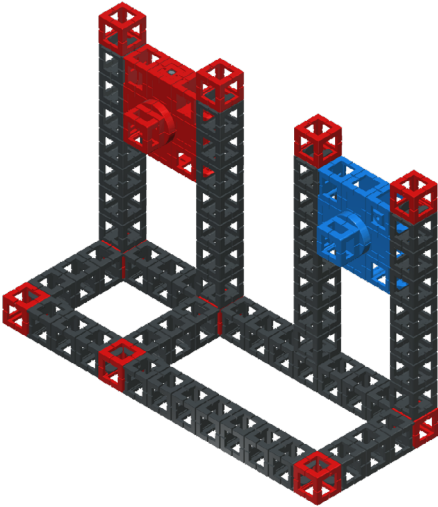



4x
Beams




4x
Blocks

3



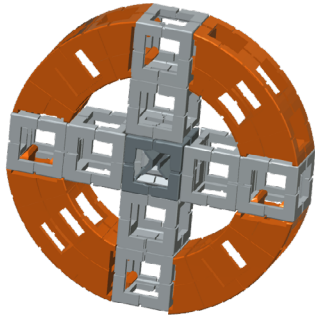



1x
Motor Module




1x
Bearing Module

4






4x
Mini Curved Beams



4x
Risers

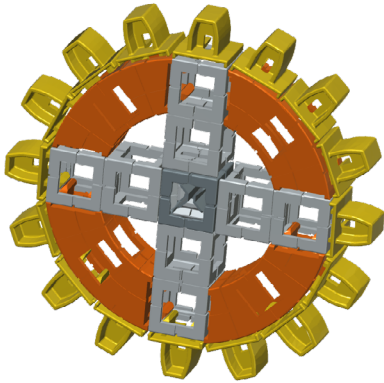


1x
Single Snap Block

Instructions:

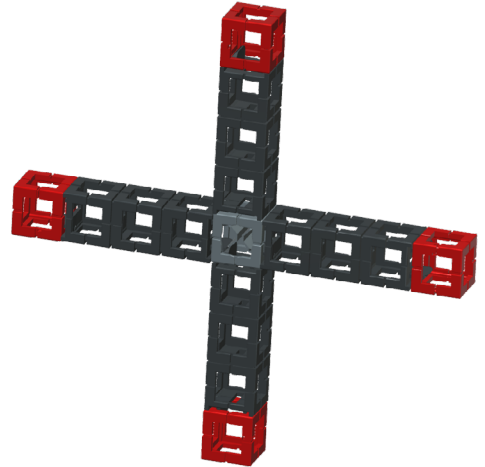
Follow the step-by-step instructions to assemble a simple gear train that produces rotary motion.

5



16x
Gear Teeth

6



4x
Half Beams

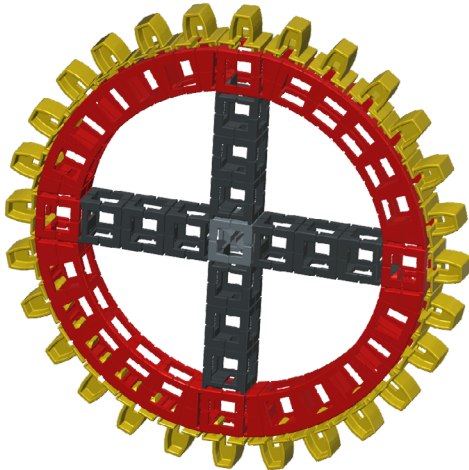


1x
Single Snap Block



4x
Blocks

7

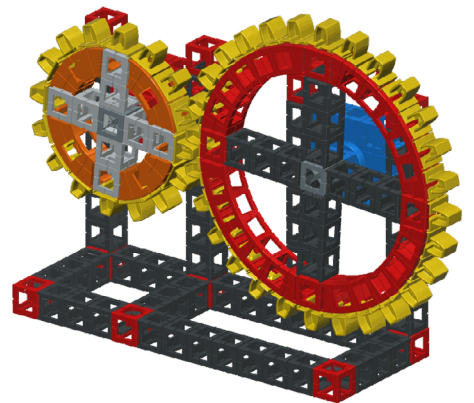


4x
Small Curved Beams



28x
Gear Teeth

8



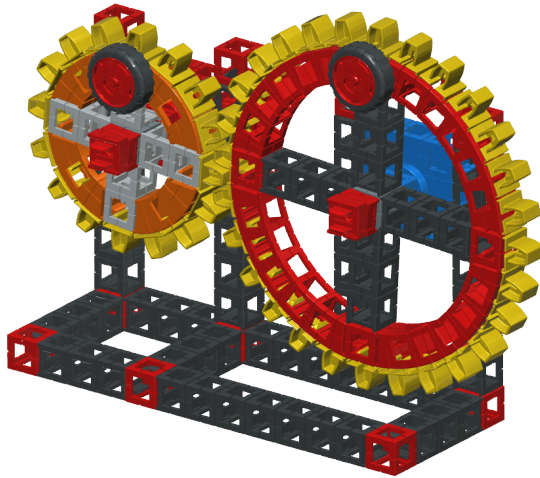
Instructions:

Place the small and large gears on the structure as shown.

Instructions:

Follow the step-by-step instructions to assemble a simple gear train that produces rotary motion.

9

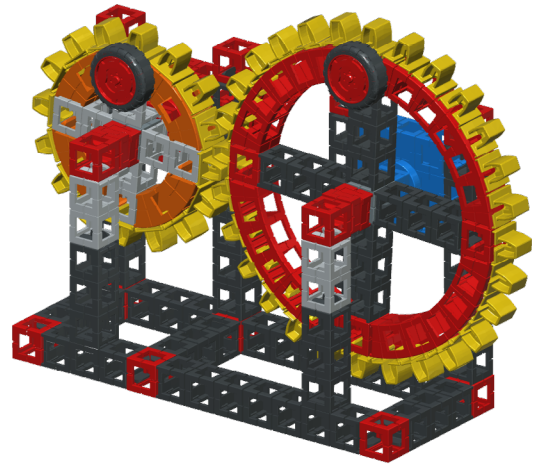


2x
Snap-In Wheels



2x
Axle Blocks

10



2x
Half Beams



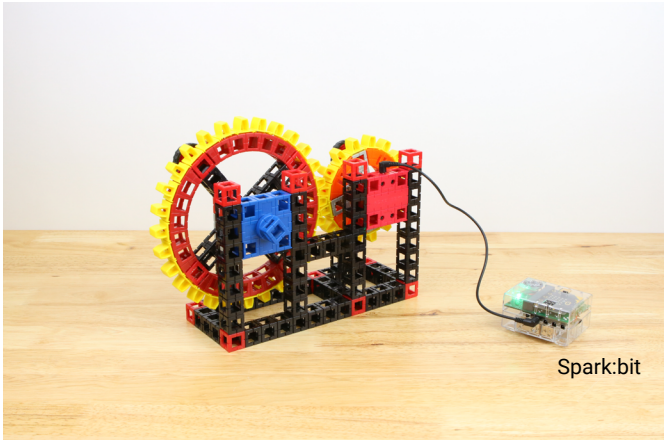
2x
Risers



2x
Blocks

Instructions:

Follow the step-by-step instructions to assemble a simple gear train that produces rotary motion.



Instructions:

Step 1: Connect a Motor Cable to the Motor Module. Connect the opposite end into Output 1 on the Spark:bit.

Step 2: Power on the Spark:bit.

Step 3: Activate Motor Override Mode on the Spark:bit using the switch located next to output 1.

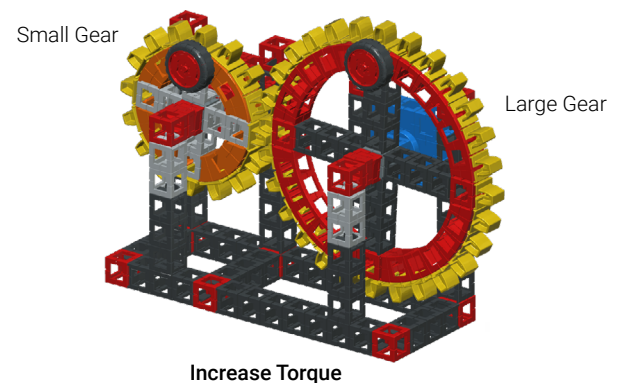
Step 4: Press the A/B buttons on the Spark:bit to activate the gear train.

In this example, a motor module is being used to drive a simple gear train. Look closely at the rotating gears and observe how they are actually rotating in opposite directions. Also, observe how the small gear is rotating faster than the large gear.

The main purpose of a gear train is to increase torque (power) or speed. The arrangement of the small and large gears will determine if the gear train will increase torque or speed.

To increase torque (a twisting force that causes rotation) using a gear train, a motor module should be directly connected to a small gear and used to drive a large gear.

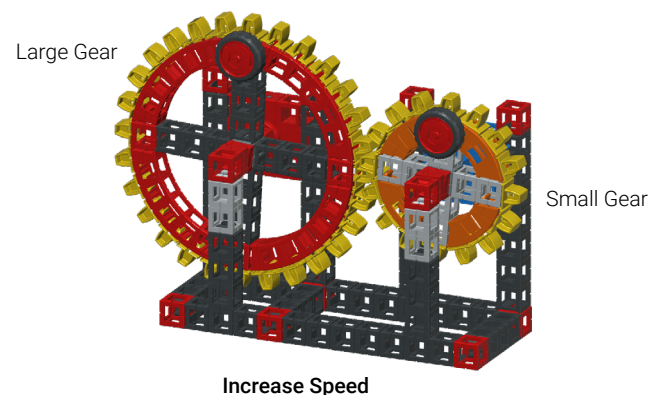
To increase speed using a gear train, a motor module should be directly connected to a large gear and used to drive a small gear.



Instructions:

Step 1: Rearrange the gears so the large gear is connected to the motor module and the small gear is connected to the bearing module.

Step 2: Activate the gear train and observe how much faster the small gear is rotating than the large gear. This gear train is now set up to increase speed.



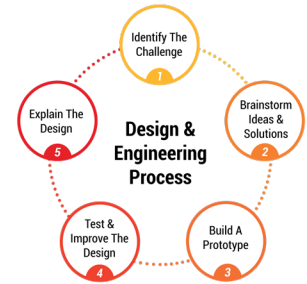
Divergent Learning Activity:

Scenario:

Kid Spark Engineering is currently accepting proposals for new and creative product inventions or innovations.

Design & Engineering Challenge:

Develop a new product or design that produces rotary motion. See example below.



Specifications/Criteria:

1. Students will work in teams of up to 4 to design and engineer a new product or design that serves a specific purpose. Teams can invent something completely new or improve an already existing product.
2. Teams must work through each step of the Design & Engineering Process to design, prototype, and refine their design. Teams will demonstrate and present their designs to the class when they are finished.
3. The product or design must be powered by the Spark:bit.
4. The design must produce rotary motion.
5. Teams must determine the overall dimensions (length, depth, and height) of the product or design, as well as any detailed specifications that are relevant to the design.
6. With each building component costing \$2, determine the total cost of the design.

Example Idea:

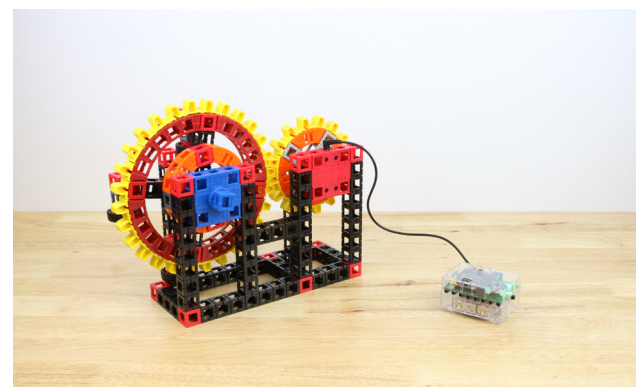
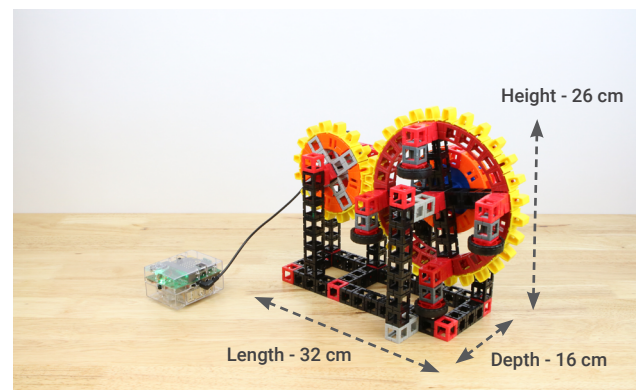
Product Innovation/Invention: Ferris Wheel (4 Chair)

Purpose: Amusement ride

Design Notes: The ferris wheel is powered by a motor module that is connected to a simple gear train. In this example, a small gear is connected to the motor module and used to drive the larger gear. This setup increases the rotating torque of the ferris wheel. The ferris wheel is controlled using the Spark:bit.






Dimensions: 32 cm x 16 cm x 26 cm (L x D x H)

Material Cost: 115 components x \$2 = \$230



Challenge Evaluation

When teams have completed the Design & Engineering Challenge, it should be presented to the teacher and classmates for evaluation. Teams will be graded on the following criteria:

-  **Design and Engineering Process:** Did the team complete each step of the Design and Engineering Process?
-  **Design Specification:** Did the team complete a design specification?
-  **Team Collaboration:** How well did the team work together? Can each student describe how they contributed?
-  **Design Quality/Aesthetics:** Is the design of high quality? Is it structurally strong, attractive, and well-proportioned?
-  **Presentation:** How well did the team communicate/explain all aspects of the design to others?

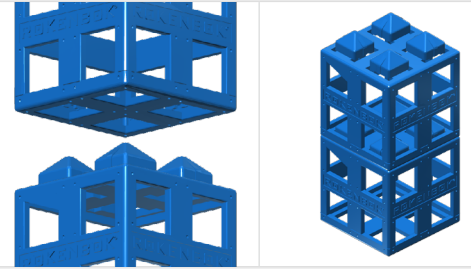
Grading Rubric	Advanced 5 Points	Proficient 4 Points	Partially Proficient 3 Points	Not Proficient 0 Points
Design & Engineering Process	<input type="checkbox"/> Completed all 5 steps of the process	<input type="checkbox"/> Completed 4 steps of the process	<input type="checkbox"/> Completed 3 steps of the process	<input type="checkbox"/> Completed 2 or fewer steps of the process
Design Specification	<input type="checkbox"/> Complete/well-detailed and of high quality	<input type="checkbox"/> Complete/opportunities for improvement	<input type="checkbox"/> Incomplete/opportunities for improvement	<input type="checkbox"/> Incomplete
Team Collaboration	<input type="checkbox"/> Every member of the team contributed	<input type="checkbox"/> Most members of the team contributed	<input type="checkbox"/> Few members of the team contributed	<input type="checkbox"/> Team did not work together
Design Quality/Aesthetics	<input type="checkbox"/> Great design/great aesthetics	<input type="checkbox"/> Good design/good aesthetics	<input type="checkbox"/> Average design/average aesthetics	<input type="checkbox"/> Poor design/poor aesthetics
Presentation	<input type="checkbox"/> Great presentation/very well-explained	<input type="checkbox"/> Good presentation/well-explained	<input type="checkbox"/> Poor presentation/poor explanation	<input type="checkbox"/> No presentation/no explanation
Points
Total Points			/25

Building Basics

The following tips will be helpful when using Kid Spark engineering materials.

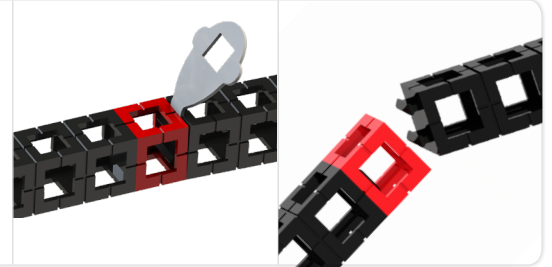
Connecting/Separating ROK Blocks:

ROK Blocks use a friction-fit, pyramid and opening system to connect. Simply press pyramids into openings to connect. To separate blocks, pull apart.



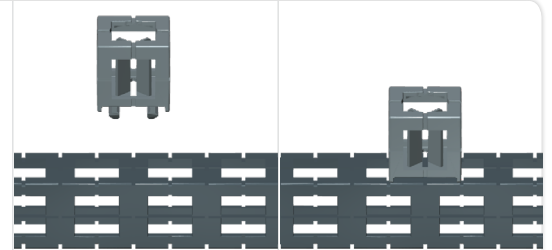
Connecting/Disconnect Smaller Engineering Materials:

Smaller engineering materials use a tab and opening system to connect. Angle one tab into the opening, and then snap into place. To disconnect, insert key into the engineered slot and twist.



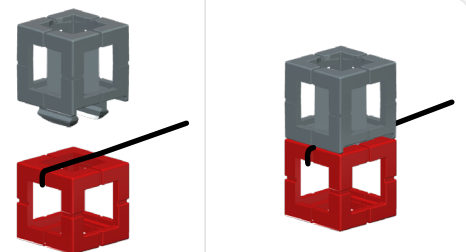
Snapping Across Openings:

Materials can be snapped directly into openings or across openings to provide structural support to a design. This will also allow certain designs to function correctly.



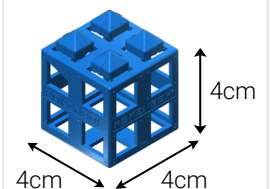
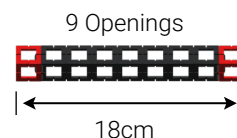
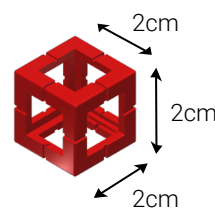
Attaching String:

In some instances, string may be needed in a design. Lay string across the opening and snap any component with tabs or pyramids into that opening. Be sure that the tabs are perpendicular to the string to create a tight fit.



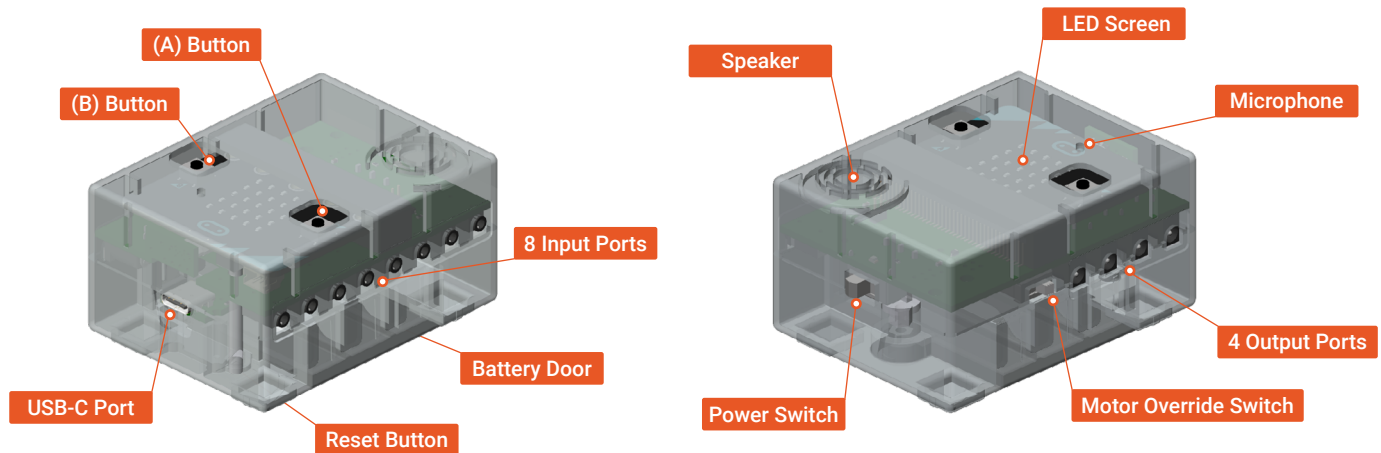
Measuring:

The outside dimensions of a basic connector block are 2 cm on each edge. This means the length, depth, and height are each 2 cm. To determine the size of a project or build in centimeters, simply count the number of openings and multiply by two. Repeat this process for length, depth, and height.



Spark:bit Robotics Controller

The Spark:bit can be programmed to read information from sensors connected to input ports, process that information into relevant commands, and send those commands to modules connected to the output ports. Users can create custom programs using Microsoft's MakeCode programming environment. The Spark:bit is powered by 3 AA batteries and can be connected to a computer using the provided USB-C cable.



Program Reset

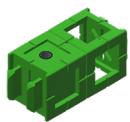
To reset the Spark:bit, press and hold the Reset button. This will reload the last program that was downloaded to it.

Motor Override Mode

Users can control Motor Modules and Light Modules without having to program the Spark:bit using Motor Override Mode. Once Motor Override Mode has been activated, connect a Motor Module or Light Module to output 1, then press the A & B buttons on the top of the Spark:bit to control the connected device.

Note: The Spark:bit must be powered on in order for Motor Override Mode to work. A flashing blue light indicates Motor Override Mode is activated. Make sure to deactivate Motor Override Mode when using the Spark:bit in programming situations.

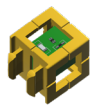
Input Sensors & Cables



Angle Sensor



Bump Sensor



Light Sensor



Sensor Cable



High Power IR Transmitter



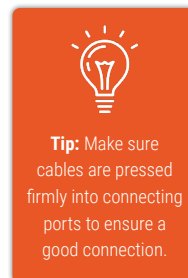
Low Power IR Transmitter



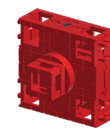
IR Sensing Receiver



Sensor Cable Extender



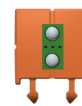
Output Modules & Cables



Motor Module



Motor/Output Cable



Light Module



Motor/Output Cable Extender